Introduction to the Simplex Algorithm Active Learning – Module 3

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Background Material

- → Almost any introductory Operations Research book has a chapter that covers the simplex algorithm. The students should read this chapter before coming to class. Two suggestions:
 - * Chapter 3 of Operations Research, by Hamdy A. Taha, Prentice Hall, 7th Edition
 - * Chapter 4 of Introduction to Operations Research by Hillier and Liberman, 7th Edition
- → The student also should read the self-contained module on the standard form of an LP problem. This module can be downloaded from:
 http://enpc2675.eas.asu.edu/lobos/iie476/stdform.doc

Lecture objectives

- ★At the end of the lecture each student should be able to:
 - * Express a Linear Programming problem in the standard form
 - * Set up the simplex tableau for a standard LP problem
 - * Find the optimal solution for an LP problem using the simplex tableau

Time Management

- **♦***Introduction 3 minutes*
- $\uparrow RAT 5$ minutes
- **♦**Lecturing on standard problem and motivation for the Simplex Algorithm 8 minutes
- **→***Individual exercise 5 minutes*
- → Lecturing on Simplex algorithm and tableau 20 minutes
- **♦** Team Exercise 5 minutes
- →Wrap up 4 minutes
- **♦** Total lecture time 50 minutes

Report Strategy Problem

◆ Suppose that Team members A and C have decided to work together in their tasks. They have decided that their skills are complementary and by working together in both of the tasks assigned to them they can do a better job than if they work independently. A has very good writing speed, he can write 4 pages per hour but his rate of grammatical errors is very high (3 errors per page). On the other hand, C is slower (2.5 pages per hour) but his error rate is very low (1 error per page). They want to write a report that will earn them the highest grade.

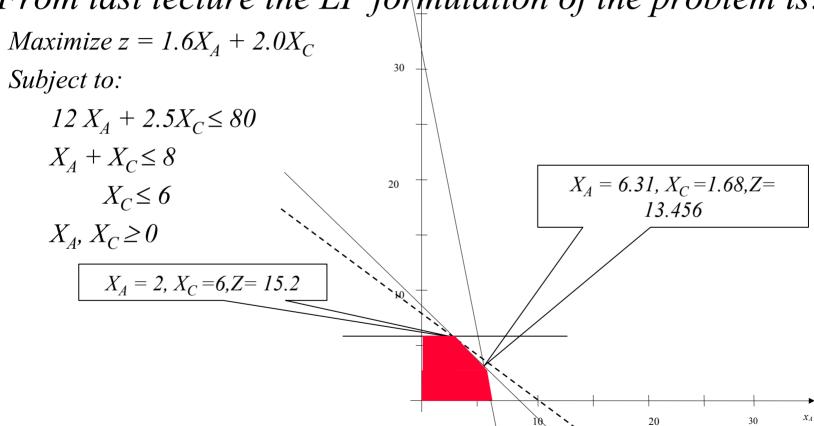
They have discovered that the grade given by the professor is very much influenced by the number of pages of the written assignments (the more pages the higher the grade assigned). However, they have also discovered that for every five errors in grammar, he deducts the equivalent of one written page, and also that the maximum number of mistakes the instructor will tolerate in an assignment is 80. Help this team of students to determine the best strategy (you need to define the meaning of this) given the total time constraint available to work in the project. The total time allocated to both of them is 8 hours. Also because of previous commitments C cannot work more than 6 hours in the project

Team exercise Readiness Assessment test(5 minutes)

- **♦** For the report strategy problem:
 - * You have found graphically the optimal solution. Based on that solution do the following exercise.
 - * You are given the alternative of increasing the number of errors allowed to 90 or to increase the number of total number of hours allowed to work in the project to 9 (for both team members). What option would you choose? Explain.
- ★At the end of the exercise each team should turn in the individual and team solutions in a single package for grading
- → The instructor may select a member of the team to present the their solution to the rest of the class

Solution





How many corner point solutions?

Solution (cont.)

To answer the second question if we increase the number of errors to 90 the first constraint would become:

$$12 X_A + 2.5 X_C \odot 90$$

Then to find the point where the two constraints intersect we would have to solve the set of equations

$$12X_A + 2.5X_C = 90$$

$$X_A + X_C = 8$$

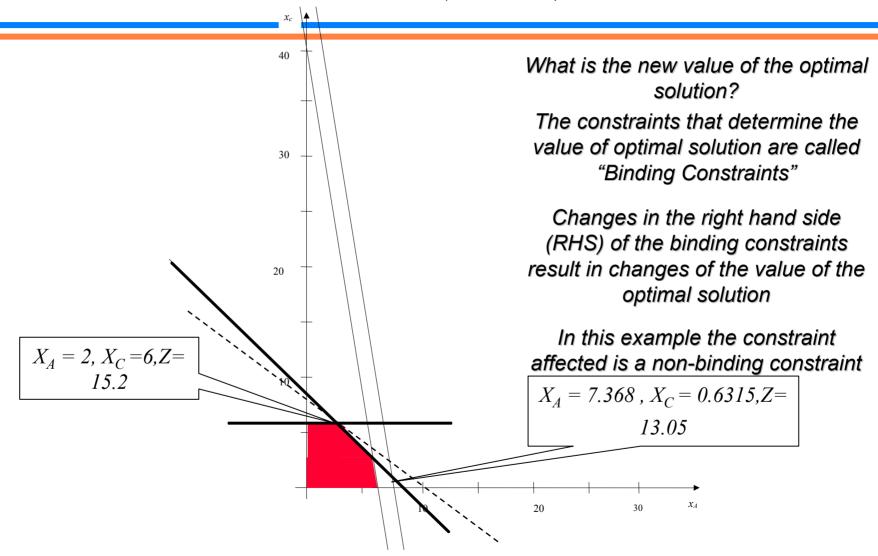
Which would give us: X_A =7.368 X_C = 0.6315. The objective function evaluated at this point would be 13.05 (No increase of the optimal solution \rightarrow non-binding constraint)

Doing the same with the other constraint we get

$$12 X_A + 2.5 X_C = 80$$
$$X_A + X_C = 9$$

Which would give us: $X_A = 6.05 X_C = 2.94$. The objective function evaluated at this point would be 15.57 \rightarrow Increase of the optimal solution \rightarrow Binding constraint We choose to increase the number of hours instead of the number of errors allowed

Solution (cont.)



Solution (cont.)

- Notice that by increasing (or decreasing) the availability of a scarce resource (hours or total number of errors allowed) the straight line (representing the constraint) moves in parallel to the original one (but note that the slope does not change)
- Also note that the "total-errors" constraint is a non-binding constraint. That is, it does not impact the <u>current</u> optimal solution. (at what point is this no longer true?)

Finding the Optimal Solution

- Unfortunately we can get the graphical solution of the LP problem only for problems with 2 and 3 decision variables
- → Therefore we need to find an alternative method to get the optimal solution of LP problems
- ♦ Some observations:
 - * We know that the optimal solution must be in a corner point (why?)
 - * We also know that a corner point is defined by the intersection of two constraints (for the 2 decision variable case we solve a different subset of two linear equations for each corner point). What about when we have three or more decision variables? Can you identify all the corner points?
 - * So what we could do is solve the subsets of linear equations corresponding to all the corner points. Then we evaluate the objective function at those corner points and the one yielding the best objective value is our optimal solution.
 - * However, since there is a large number of corner points (how many?) this is impractical. We need a smart way to search for the optimal solution. This is what the the simplex algorithm does for us.

Introduction to the Simplex Method

- **♦ Simplex Method** .- An algebraic, <u>iterative method</u> to solve linear programming problems.
- → The simplex method identifies an initial <u>basic solution</u> (Corner point) and then systematically moves to an <u>adjacent basic solution</u>, which improves the value of the objective function. Eventually, this new basic solution will be the optimal solution.
- → The simplex method requires that the problem is expressed as a standard LP problem (see <u>module on Standard Form</u>). This implies that all the constraints are expressed as equations by adding <u>slack or surplus variables</u>.
- → The method uses Gaussian elimination (sweep out method) to solve the linear simultaneous equations generated in the process.

Example of use of Slack and Surplus Variables

$$6 X_1 + 3X_2 \le 10 \quad (1)$$

$$3 X_1 + X_2 = 7 \quad (2)$$

$$7 X_1 + 4X_2 + X_3 \ge 10 \quad (3)$$

→ Since (1) and (3) are inequalities we need to <u>add a slack</u> (1) and <u>subtract a surplus</u> variable (3) accordingly. Then the inequalities can be expressed as equations of the form:

$$6X_1 + 3X_2 + S_1 = 10$$
 (1')
 $3X_1 + X_2 = 7$ (2')
 $7X_1 + 4X_2 + X_3 - S_3 = 10$ (3'),

Where S_1 is a slack variable and S_3 is a surplus variable. What is the physical meaning of these variables?

Example Reddy Mikks Problem

Original Reddy Mikks Problem

$$Maximize z = 3X_E + 2X_I$$

Subject to:

$$X_E + 2X_I \le 6 \tag{1}$$

$$2X_E + X_I \le 8 \tag{2}$$

$$-X_E + X_I \le 1 \tag{3}$$

$$X_I \le 2 \tag{4}$$

$$X_E, X_I, \geq 0$$

Reddy Mikks Problem with slack variables

$$\begin{aligned} \textit{Maximize } z &= 3X_E + 2X_I + 0S_I + \\ 0S_2 &+ 0S_3 + 0S_4 \end{aligned}$$

Subject to:

$$X_{E} + 2X_{I} + S_{I} = 6 (1)$$
 $2X_{E} + X_{I} + S_{2} = 8 (2)$
 $-X_{E} + X_{I} + S_{3} = 1 (3)$
 $X_{I} + S_{4} = 2 (4)$

$$X_E, X_I, S_1, S_2, S_3, S_4 \ge 0$$

Example Inspection Problem

Original Inspection Problem

$$Minimize Z = 40 X_1 + 36 X_2$$

Subject to:

$$5X_1 + 3X_2 \ge 45$$

$$X_1 \le 8$$

$$X_2 \le 10$$

$$X_1, X_2 \geq 0$$

Inspection Problem with slack and surplus variables

Minimize
$$Z = 40 X_1 + 36X_2 + 0S_1 + 0S_2 + 0S_3$$

Subject to:

$$5X_1 + 3X_2 - S_1 = 45$$

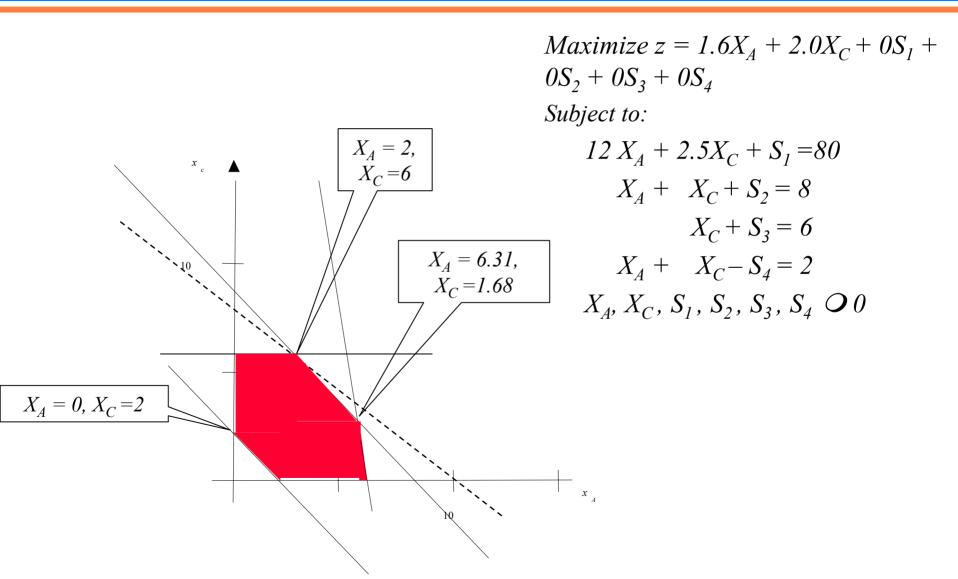
 $X_1 + S_2 = 8$
 $X_2 + S_3 = 10$

$$X_{1}, X_{2} S_{1}, S_{2}, S_{3} \geq 0$$

Individual Exercise (3 min)

- For the report strategy problem add the following constraint $X_A + X_C \ge 2$
- →For the resulting LP Model introduce the appropriate slack and surplus variables in the constraints and objective function
- Find the maximum number of basic solutions and identify the subset of Basic Feasible Solutions on the graph.

Solution



Standard Form Linear Programming

- → We define the standard form of a linear programming problem as:
 - * One whose objective function is maximization
 - * One whose constraints are expressed as equations and whose right hand side is non-negative (after the introduction of slack and surplus variables)
 - * One in which all the decision variables are non-negative

Terminology

- \uparrow A **solution** is any specification of values for the decision variables.
- → A feasible Solution is a solution for which all the constraints are satisfied.
- → The **feasible region** is the set of all feasible solutions.
- An Optimal Solution is a feasible solution that has the most favorable value of the objective function.
- → A Corner-Point Solution corresponds to a solution of the subset of equations corresponding to the constraints meeting at that corner point (vertex)
- ightharpoonup A **Corner-point feasible** (CPF) solution is a solution that lies at a corner of the feasible region .
- **♦** A **Basic Solution** is a corner-point solution
- *→* A **Basic Feasible Solution** is a CPF solution for which all the variables are greater than or equal to zero.

Conceptual Outline of the Steps of the Simplex Algorithm

- **Step 0:** Using the standard form determine a starting basic feasible solution by setting n-m non-basic variables to zero.
- → Step 1: Select an entering variable from among the current non-basic variables, which gives the largest per-unit improvement in the value of the objective function. If none exists stop; the current basic solution is optimal. Otherwise go to Step 2.
- → Step 2: Select a leaving variable from among the current basic variables that must now be set to zero (become non-basic) when the entering variable becomes basic.
- → Step 3: Determine the new basic solution by making the entering variable, basic; and the leaving variable, non-basic, and return to Step 1.

Simplex Method in Tableau Format

- → The tableau format allows us to represent the problem compactly and more easily solve it.
- → We merely record the coefficients of the problem only.
- →In order to use the Tableau Method we need to do three things first:
 - * Represent the LP problem in standard form
 - * Represent the objective function as an equation

$$z - \sum_{j} c_{j} \chi_{j} = 0;$$

where z is the value of the objective function.

* Determine the initial basic solution

Setting up the Reddy-Mikks Problem

→ For Instance the Reddy-Mikks Problem:

Maximize
$$z = 3X_E + 2X_I$$

Subject to:

$$X_E + 2X_I \le 6 \quad (1)$$

$$2X_E + X_I \le 8 \quad (2)$$

$$-X_E + X_I \le 1$$
 (3)

$$X_I \le 2 (4)$$

$$X_E, X_L \geq 0$$

→ Is expressed as:

Maximization is implied by the (+1)z since it is the objective function of the standard form.

Because they provide an immediate basic feasible solution we choose the slack variables as the initial basic variables

Simplex Tableau

- → The tabular form of the simplex method uses a simplex **tableau** to display the system of equations yielding the current basic feasible solution.
- → There are different ways to design the tableau a common design is as follows

Initial Tableau for the R-M problem (Iteration 0)

Header ——	Basic Var.	Eq.	Z	X_E	X_{I}	S_1	S_2	S_3	S_4	Rt Side (Sol)
Objective Function	Z	0	1	-3	-2	0	0	0	0	0
	S_1	1	0	1	2	1	0	0	0	6
Constraints —	S_2	2	0	2	1	0	1	0	0	8
Constraints	S_3	3	0	-1	1	0	0	1	0	1
	S_4	4	0	0	1	0	0	0	1	2

Steps of the Simplex Algorithm

- ♦ Step 0: Optimality test: the current basic feasible solution is optimal if every coefficient in row 0 of the tableau is non-negative. If it is, stop; if not perform an additional iteration.
- → Step 1: Determine the entering variable by selecting the variable having the most negative coefficient in row 0. The corresponding column is called the *pivot column*.
- → Step 2: Determine the leaving variable by applying the minimum ratio test:
 - * Pick out each coefficient in the **pivot column** having a positive value.
 - * Divide the right hand of each row by each of these positive coefficients.
 - * Determine the smallest of these ratios
 - * The basic variable for the row corresponding to the smallest ratio is the leaving variable. Replace this variable with the entering variable in the next tableau.
 - * The row with the smallest ratio is called the *pivot row*. The number in the intersection of the pivot column and row is the *pivot element*.
- → Step 3: Solve for the new BFS by using elementary row operations.

Iteration 0 (Steps 0,1,2)

	Iter-	Basic	Eq.	Z	X_{E}	X_{I}	S_1	S_2	S_3	S_4	RHS
	ation	Var.									(Sol)
		Z	0	1	- 3	-2	0	0	0	0	0
·		S_1	1	0	1	2	1	0	0	0	6
·	0	S_2	2	0	- 2	1	0	1	0	0	8
1		S_3	3	0	-1	1	0	0	1	0	1
		S_4	4	0	0	1	0	0	0	1	2

Pivot Element

Entering Variable: Select the variable with the most negative coefficient in the objective function

Leaving Variable:
Smallest ratio obtained
by dividing the RHS of
each row by the positive
coefficients of the
entering variable
(Column)

6/1

8/2

Iteration 0 (Step 3)



To get the new BFS we perform the following steps

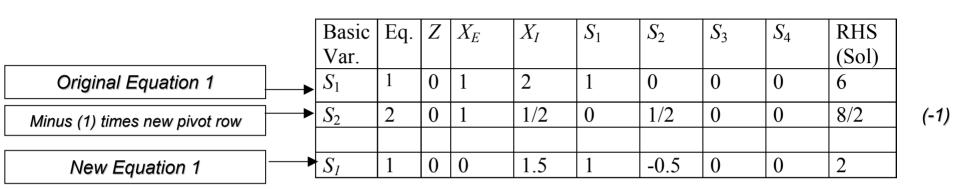
- 1. Divide the pivot row by the pivot element and call it the "new pivot row". Copy the result in the tableau for the next iteration
- 2. For every row of the current tableau (excluding the pivot row) subtract the product of its pivot-column coefficient times the new pivot row. Copy the result in the corresponding row of the next-iteration tableau. Make sure to properly identify the new basic variable.



M-R Example: New pivot 1:

Iter-	Basic Var.	Eq.	Z	X_E	X_{I}	S_1	S_2	S_3	S_4	RHS
ation	Var.									RHS (Sol)
	Z	0	1							
	S_1	1	0							
1	X_E	2	0	1	1/2	0	1/2	0	0	8/2
	S_3	3	0							
	S_4	4	0							

M-R Example: New Row 1



Resulting Tableau (Partial)

Iter-	Basic	Eq.	Z	X_E	X_I	S_1	S_2	S_3	S_4	RHS
ation	Var.									(Sol)
	Z	0	1							
	S_1	1	0	0	1.5	1	-0.5	0	0	2
	X_E	2	0	1	0.5	0	0.5	0	0	4
1	S_3	3	0							
	S_4	4	0							

Team exercise (5 minutes)

- →Perform the operations needed to get the resulting equation 0
- → The instructor might select a member of the team to present the team's solution to the rest of the class

Result of Exercise

		Basic Var.	Eq.	Z	X_E	X_I	S_1	S_2	S_3	S_4	RHS (Sol)
Original Equation 0	—	\overline{Z}	0	1	-3	-2	0	0	0	0	0
Minus (-3) times new pivot row	 	S_2	2	0	1	1/2	0	1/2	0	0	8/2
New Equation 0	 	·Z	0	1	0	-0.5	0	1.5	0	0	12

Iteration 1

Iter-	Basic	Eq.	Z	X_{E}	S_1	S_2	S_3	S_4	RHS	
ation	Var.								(Sol)	
	Z	0	1	0	0	1.5	0	0	12	
										2/1.
	X_E	2	0	1	0	0.5	0	0	4	4/0.
1	S_3	3	0	0	0	0.5	1	0	5	5/1.
ı	S_4	4	0	0	0	0	0	1	2	2/1.

Entering Variable: Select the variable with the most negative coefficient in the objective function

Leaving Variable: Smallest ratio obtained by dividing the RHS of each row by the positive coefficients of the entering variable (Column)

Iteration 2

Iter-	Basic	Eq.	Z	X_E	X_I	S_1	S_2	S_3	S_4	RHS
ation	Var.									(Sol)
	Z	0	1	0	0	0.33	1.33	0	0	12.66
	X_{I}	1	0	0	1	0.66	-0.33	0	0	1.33
2	X_{E}	2	0	1	0	-0.33	0.66	0	0	3.33
	S_3	3	0	0	0	-1.0	1.0	1	0	3
	S_4	4	0	0	0	-0.66	0.33	0	1	0.66

Since all the coefficients in the objective function are positive we stop: We have found the optimal Solution

Using the Simplex procedure for Minimization problems

- \bigstar A minimization problem can be converted to a maximization problem just by multiplying the objective function by (-1).
- → Once this is done the problem is solved exactly the same as the maximization problem
- **♦** Example:

Minimize $z = x_1 - 3x_2 - 2x_3$	Maximize $(-z) = -x_1 + 3x_2 + 2x_3$	$Maxz + x_1 - 3x_2 - 2x_3 = 0$
Subject to:	Subject to:	Subject to:
$3x_1 - x_2 + 2x_3 \leq 7$	$3x_1 - x_2 + 2x_3 \leq 7$	$3x_1 - x_2 + 2x_3 + S_1 = 7$
$-2x_1 + 4x_2 + 2x_3 \le 12$	$-2x_1 + 4x_2 + 2x_3 \leq 12$	$-2x_1 + 4x_2 + 2x_3 + S_2 = 12$
$-4x_1 + 3x_2 + 8x_3 \le 10$	$-4x_1 + 3x_2 + 8x_3 \leq 10$	$-4x_1 + 3x_2 + 8x_3 + S_3 = 10$
$x_1, x_2 \geq 0$	$x_1, x_2 \geq 0$	$x_{1}, x_{2}, S_{1}, S_{2}, S_{3} \ge 0$

Team Exercise (5 minutes)

- ♦ Setup the tableau and perform one iteration of the Simplex Algorithm
- → Answer the following question: How would you evaluate the efficiency of the simplex algorithm?
- → The instructor may select a member of the team to present the team's solution to the rest of the class

Simplex Solution of Minimization Problem

Iter-	Basic	Eq	Z	X_I	X_2	X_3	S_1	S_2	S_3	RHS
ation	Var.									(Sol)
0	Z	0	-1	1	-3	-2	0	0	0	0
	S_1	1	0	3	-1	2	1	0	0	7
	S_2	2	0	-2	4	0	0	1	0	12
	S_3	3	0	-4	3	8	0	0	1	10
1	Z	0	-1	-0.5	0	-0.5	0	0.75	0	9
	S_1	1	0	2.5	0	2.5	1	0.25	0	10
	X_2	2	0	-0.5	1	0.5	0	0.25	0	3
	S_3	3	0	-2.5	0	6.5	0	-0.75	1	1
2	Z	0	-1	0	0	0	0.2	0.8	0	11
	X_1	1	0	1	0	1	0.4	0.1	0	4
	X_2	2	0	0	1	1	0.2	0.3	0	5
	S_3	3	0	0	0	9	1.0	-0.5	1	11

Solution

- **♦**Efficiency of the simplex algorithm
 - * One way to assess the efficiency of the simplex algorithm is to count the number of iteration needed to arrive to the optimal solution and to compare this against the total number of corner point solutions given by the formula:

$$\binom{n}{m} = \frac{n!}{(n-m)!m!}$$

* (n) = number of variables, (m) = number of equations

Assignment

- Setup the tableau and perform the first iteration for the report strategy problem
- → Using the software provided with your textbook solve the Reddy-Mikks and the report strategy problem

Corner Point Solution

- → Previously we learned that a corner point solution corresponds to a solution of the subset of equations corresponding to the constraints meeting at that corner point (vertex)
- → Thus if we have m constraints and n dimensions we use only n equations to find the corner point solution.